

Batch Proposals for Model-Based Multi-Objective Optimization in the context of SVM tuning

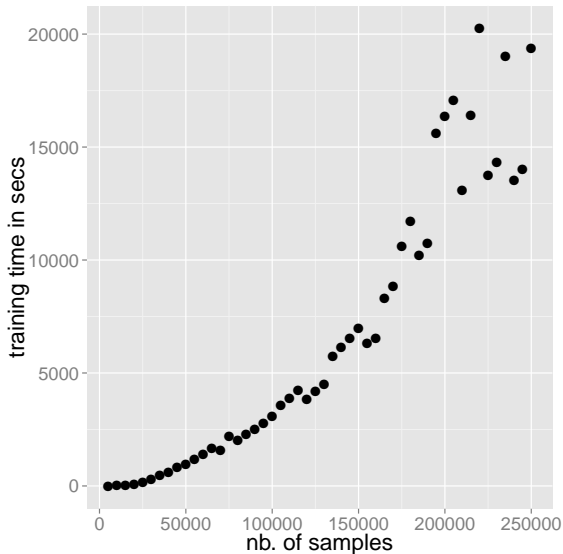
Daniel Horn

TU Dortmund

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Complexity of Support Vector Machine training

- **Problem:**
Complexity of SVM training is $\mathcal{O}(n^2)$... $\mathcal{O}(n^3)$
- **Example:**
Training of LIBSVM on {5000, 10000, ..., 250000} samples of the poker dataset
- **Solution:**
Approximate SVM training
- **Problem:**
Which of the many approximation algorithms to use?



- **We expect:** Every solver has a trade-off between training time and prediction error: Given more time, a solver (should) reach a better solution.
- **Our goal:** Analyze this trade-off! Solve the multi-criteria optimization problem with respect to the two objectives error and training time by varying the parameters.
- **The challenge:** Optimizing 2 expensive objectives in a 3-to-4-dimensional parameter space.
- **Our approach:** Replace standard grid search with more sophisticated PAREGO-algorithm.

Extend the PAREGO-Algorithm

- 1 Scalarize objectives using the augmented Tchebycheff norm

$$u(x) = - \max \left[\vec{w}(\vec{f}(\vec{x}) - \vec{i}) \right] + \rho \sum \vec{w}(\vec{f}(\vec{x}) - \vec{i})$$

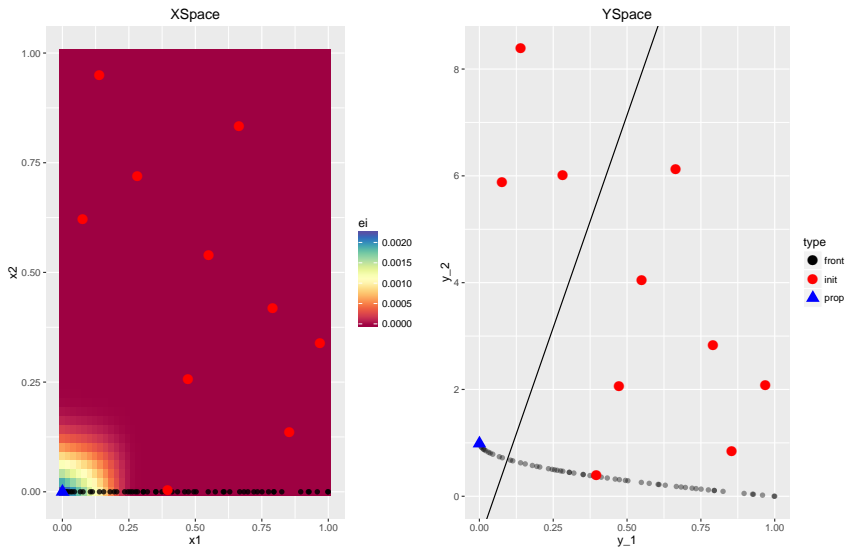
with ideal point \vec{i} and uniformly distributed weight vector \vec{w} ($\sum w_i = 1$) and fit surrogate model to the respective scalarization

- 2 Single-obj. optimization of expected improvement (EI)

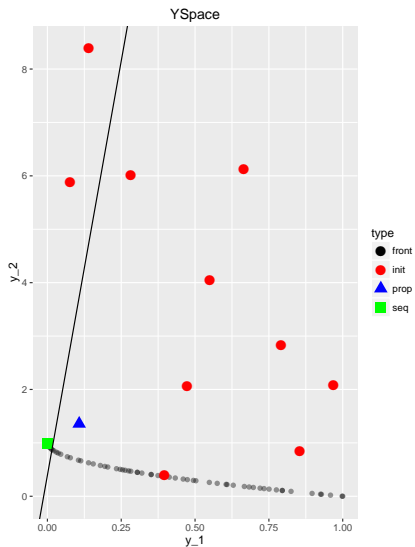
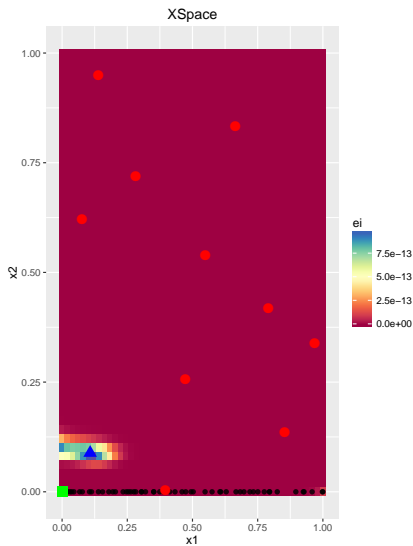
Modification: **Increase the number and diversity of randomly drawn weight vectors**

- If N points are desired, cN ($c > 1$) weight vectors are considered
- Greedily reduce set of weight vectors by excluding one vector of the pair with minimum distance
- Scalarizations implied by each weight vector are computed
- Fit and optimize models for each scalarization
- Optima of each model build the batch to be evaluated

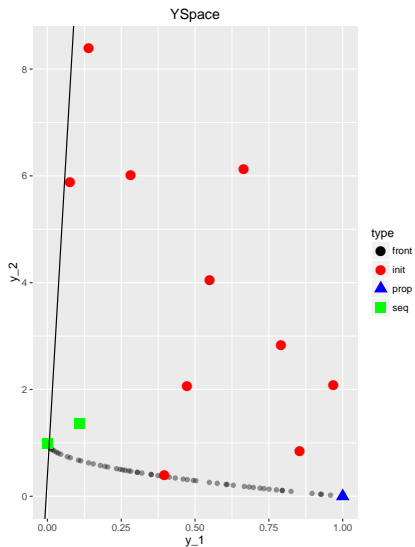
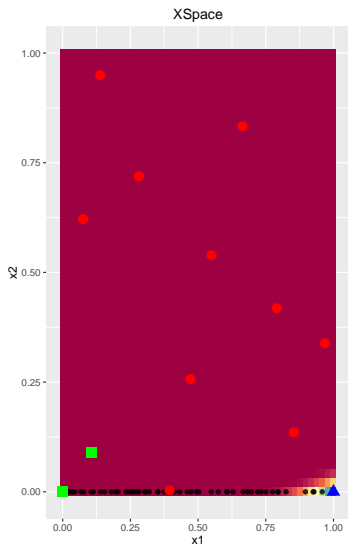
Animation of PAREGO



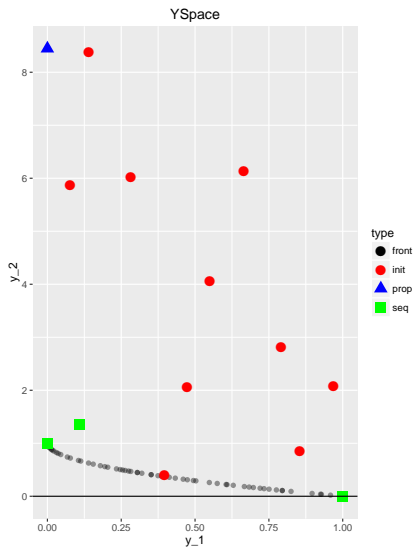
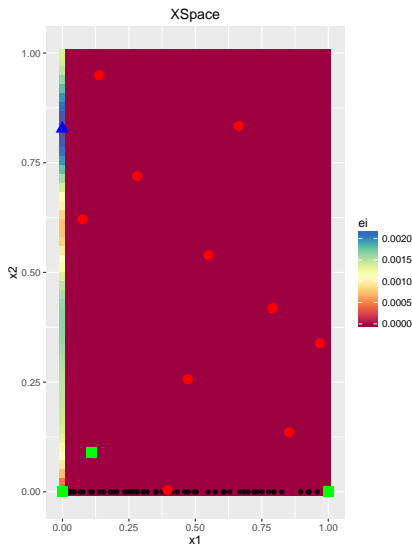
Animation of PAREGO



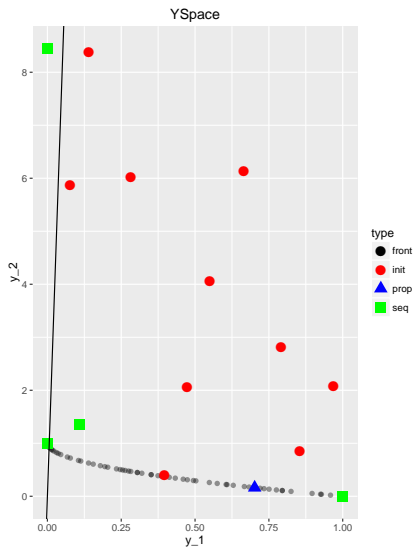
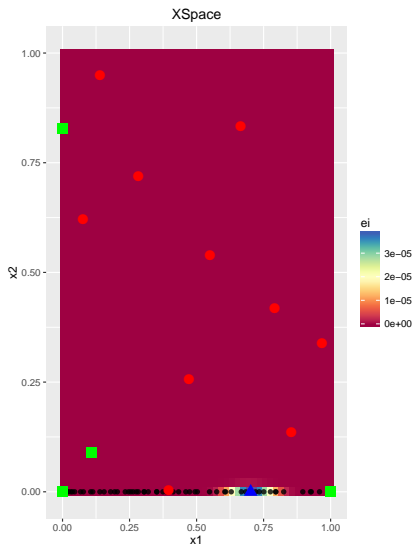
Animation of PAREGO



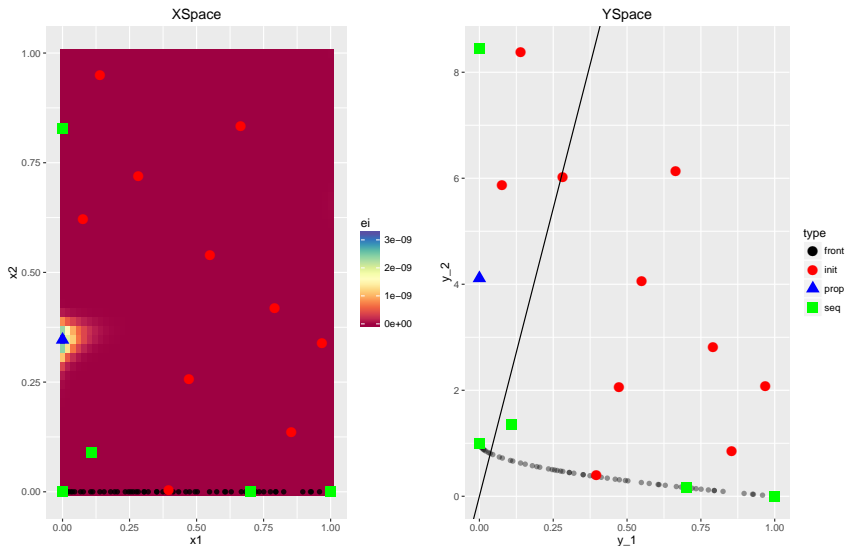
Animation of PAREGO



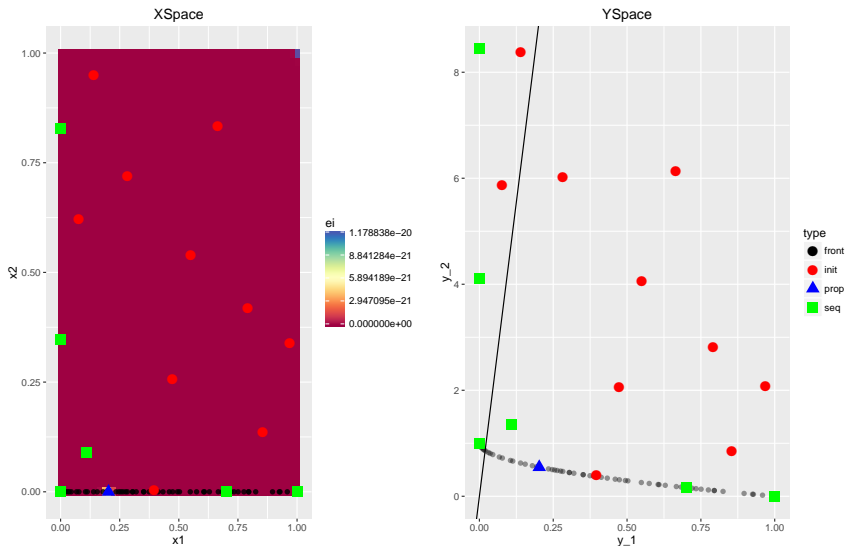
Animation of PAREGO



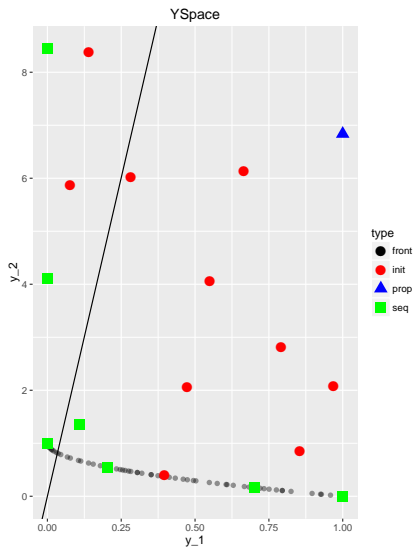
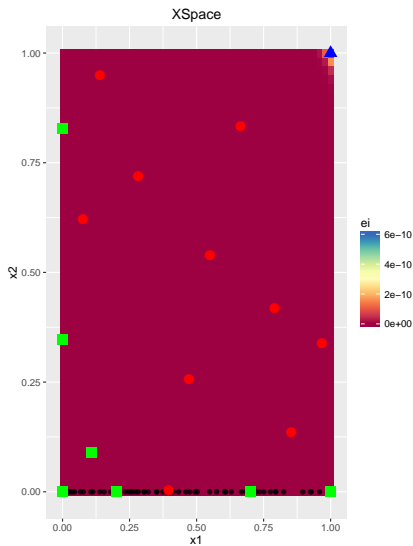
Animation of PAREGO



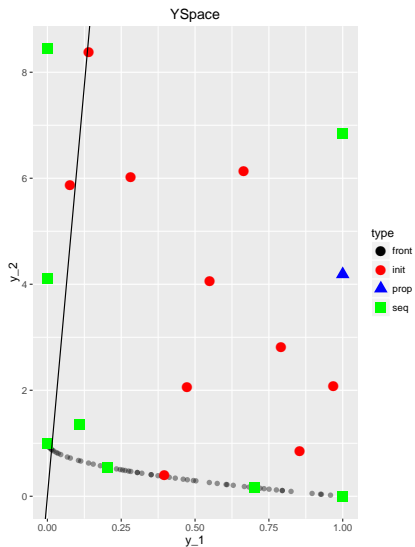
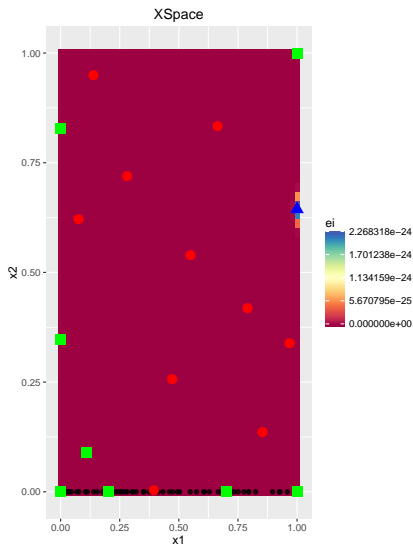
Animation of PAREGO



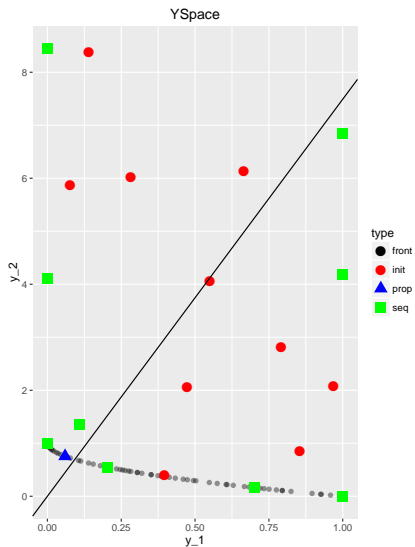
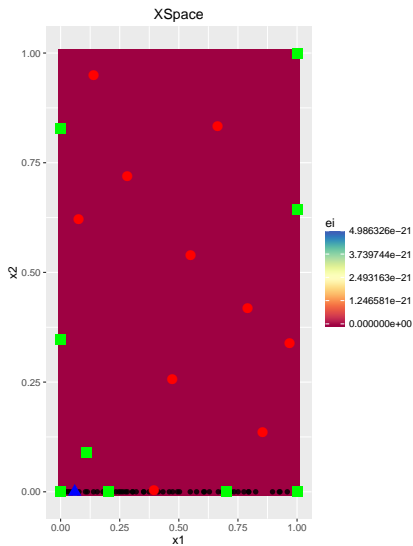
Animation of PAREGO



Animation of PAREGO



Animation of PAREGO



The design of our study

The parameters (C, γ) of the SVM itself were optimized over $2^{[-15,15]}$ respectively. Every solver has further approximation parameters:

SVM solver	Parameters	Optimization Space
LLSVM	Matrix rank	$2^{[4,11]}$
LIBSVM	ϵ (Accuracy)	$2^{[-13,-1]}$
LASVM	ϵ (Accuracy), #Epochs	$2^{[-13,-1]}$, $2^{[0,7]}$
LIBBVM/CVM	ϵ (Accuracy)	$2^{[-19,-1]}$
SVMperf	ϵ (Accuracy), #Cutting planes	$2^{[-13,-1]}$, $2^{[4,11]}$

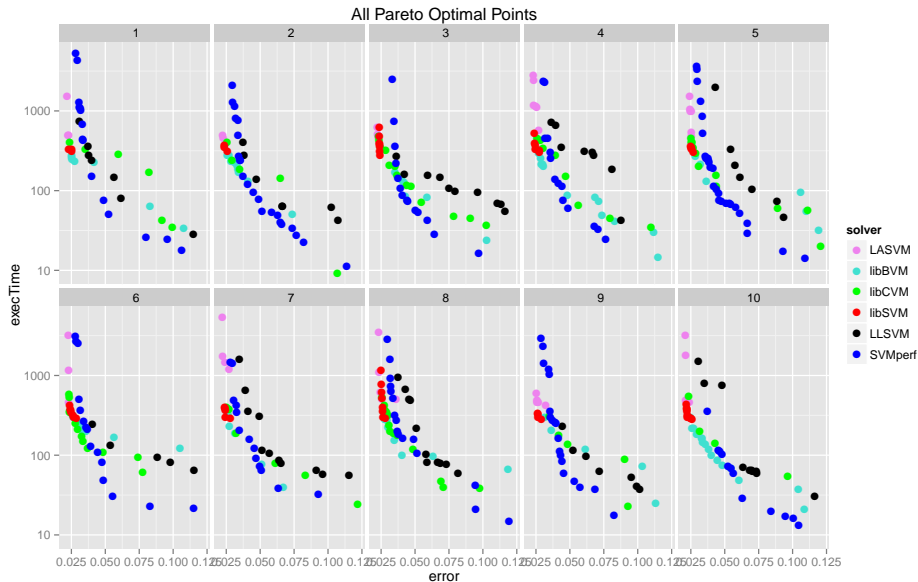
Additional parameters set to default values.

Datasets

data set	# points	# features	class ratio	sparsity
wXa	34 780	300	34.45	95.19 %
aXa	36 974	123	3.17	88.72 %
protein	42 153	357	1.16	71.46 %
mnist	70 000	780	0.96	80.76 %
vehicle	98 528	100	1.00	0 %
shuttle	101 500	9	0.27	0.23 %
spektren	175 090	22	0.80	0 %
ijcnn1	176 691	22	9.41	40.91 %
arthrosis	262 142	178	1.19	0.01 %
cod-rna	488 565	8	2.00	0.02 %
covtype	581 012	54	1.05	78 %
poker	1 025 010	10	1.00	0 %

Table : Overview of the data sets.

Example: MNIST (appr. 2 weeks computation time)



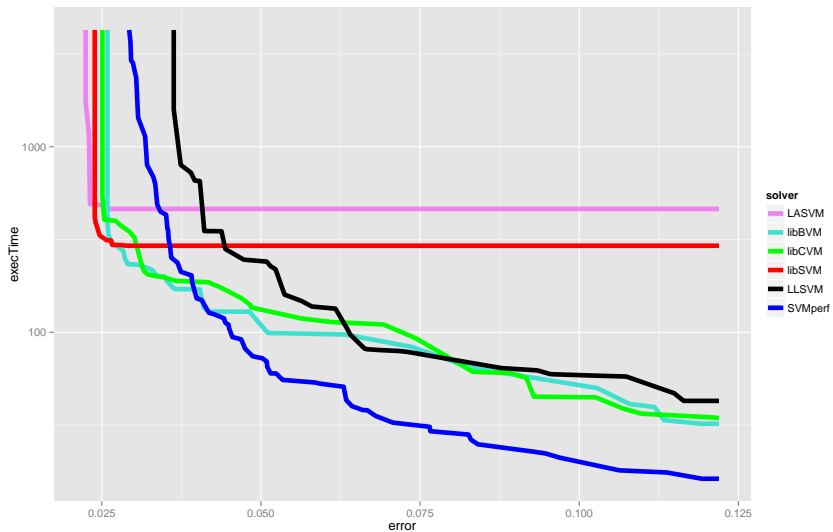
Further Analysis of the Results

- Too much information – systematic analysis needed
- Look at the common Pareto front

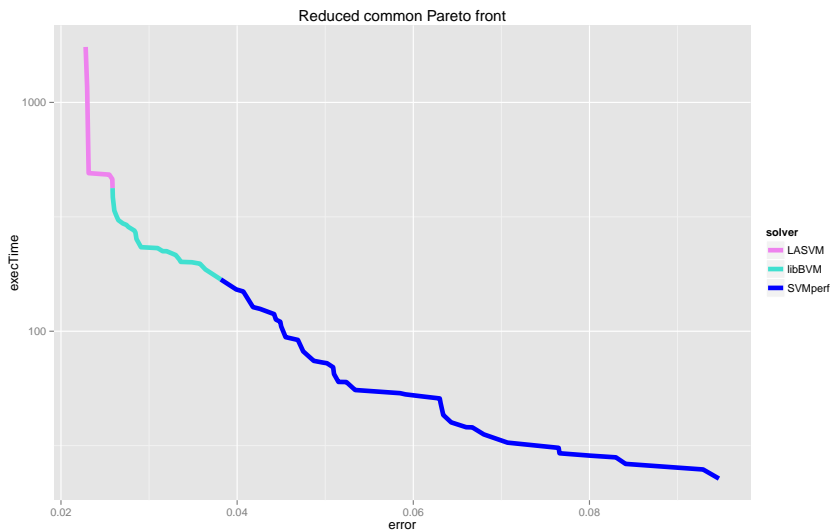
The Common Pareto Front: For every given trade-off give the best algorithm from a portfolio of algorithm. The portfolio should be as small as possible while the corresponding front should be as good as possible.

- Remove completely dominated solvers
- Calculate the empirical attainment function (eaf)
- Select *best* subset of solvers with respect to the Augmentend Tschebyscheff Norm
- Decide, which solver covers which part of the common front

Example: MNIST



Example: MNIST



Batch Proposals

Sequential Computation Time of the MNIST example:

- 10 Replications · 6 Algorithms · 220 Function Evaluations · 1 hour per function evaluation = 13 200 hours \approx 2 years
- Parallelization over experiments: 220h per experiment \rightarrow our Batch Computer would allow only \approx 10 parallel experiments
- Make 20 function evaluation at the same time

Idea of Batch Proposals:

- Propose N_1 points in a Batch \rightarrow Evaluate all points on N_2 parallel systems \rightarrow speed up of factor $\min(N_1, N_2)$ (ideally ...)
- Super computer allow very high N_2 \rightarrow we need algorithms that allow high values of N_1
- We proposed batch mechanisms for known algorithms and benchmarked them for $N_1 = 4$

Batch Proposal for MSPOT

- 1 Individual models for each objective
- 2 Multi-obj. optimization of mean response on each model, e.g. using NSGA-II
- 3 Select final candidates from NSGA-II result based on hypervolume contribution to the current approximation

Modification: **Iterated indicator-based candidate selection**

- Select point of the candidate set having the highest contribution
- Add point to the Pareto front approximation
- Update the contributions of the remaining points
- Repeat until N points for a batch evaluation have been selected

Batch-Proposal for DIB (SMS-EGO, ϵ -EGO)

- 1 Singl-obj. optimization of aggregating infill criterion:
Calculate contribution of the lower confidence bound $I(\vec{x}) = \hat{y}(\vec{x}) + \lambda \hat{s}(\vec{x})$ (LCB) of representative solution to the current front approximation
 - **SMS-EGO:** Contribution with regard to the hypervolume indicator. For ϵ -dominated (\preceq_ϵ) solutions, and a respective penalty $\Psi(\vec{x}) = -1 + \prod_{j=1}^m (1 + (I(\vec{x}) - y_j^{(i)}))$ is added
 - ϵ -**EGO:** Contribution with regard to the additive ϵ -indicator

Modification: **Use simulated evaluations for candidate generation**

- The proposed point \vec{x}^* is not directly evaluated, but the LCB $I(\vec{x}^*)$ is added to the current approximation without refitting the model
- Repeat until N points for a batch evaluation have been found

Benchmark: Test functions

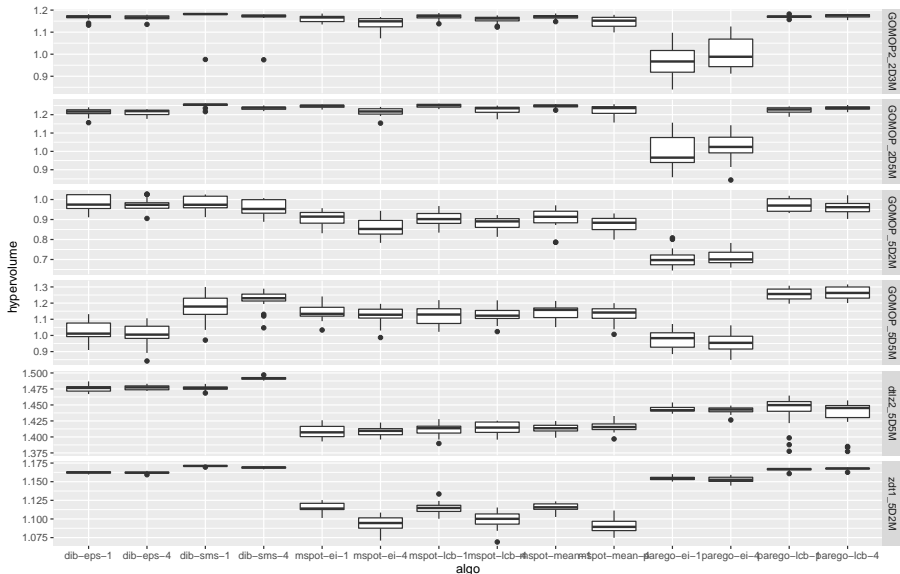
Name	d	m	Internal test functions
GOMOP-22	2	2	Branin, 3-Hump-Camel ($\vec{x} \in [-2, 2]^2$)
GOMOP-25	2	5	Branin, 3-Hump-Camel ($\vec{x} \in [-2, 2]^2$), Hartman, Goldstein-Price, 6-Hump-Camel ($x_1 \in [-2, 2], x_2 \in [-1, 1]$)
GOMOP-52	5	2	Hartman, Rastrigin ($\vec{x} \in [-0.5, 0.5]^5$)
GOMOP-55	5	5	Hartman, Rastrigin ($\vec{x} \in [-0.5, 0.5]^5$), Rosenbrock, Zahkharov ($\vec{x} \in [-1, 1]^5$), Powell ($\vec{x} \in [-1, 1]^5$)
ZDT1	5	2	
ZDT2	5	2	
ZDT3	5	2	
DTLZ2	5	2	
DTLZ2	5	5	

Expensive setting: Total budget of $n_{\text{total}} = 40d$, $\text{init.design} = 4d$

Benchmark: Experimental Setup

- In addition to the four MBMO algorithms, Random Search and NSGA2 were run as baselines
- Every MBMO algorithm was run as single-point and 4-point variant
- ParEGO was run with LCB and EI as infill criterion, MSPOT with Mean, LCB and EI
- Reference set: union of all Pareto-optimal solutions
- All approximations and reference sets are normalized to the interval $[1, 2]^m$
- 3 indicators: unary R2, unary hypervolume, and additive ε
- 20 replications per run
- Significant improvements ($p = 0.05$) with respect to a pairwise Wilcoxon test
- Tests vs. baselines Random Search and NSGA-II
- Tests Singlepoint versus Multipoint

Results



We implemented the taxonomy and the 4 MBMO algorithms ParEGO, SMS-EGO, ε -EGO, and MSPOT as its instantiations in our R-package. Our package supports:

- Algorithms for single- und multi-objective optimization
- A large number of different infill criteria, infill optimizers, surrogate models, ...
- A modular structure, easy to extend

My Literature

- Horn, D., Demircioglu, A., Bischl, B., Glasmachers, T., Wagner, T., and Weihs, C. (201Xa). Multi-objective selection of algorithm portfolios. *Archives of Datascience*. Submitted.
- Horn, D., Demircioglu, A., Bischl, B., Glasmachers, T., and Weihs, C. (201Xb). A comparative study on large scale kernelized support vector machines. *Advances in Data Analysis and Classification*. Under Revision.
- Horn, D., Wagner, T., Biermann, D., Weihs, C., and Bischl, B. (2015). Model-Based Multi-objective Optimization: Taxonomy, Multi-Point Proposal, Toolbox and Benchmark. In *Evolutionary Multi-Criterion Optimization*, volume 9018 of *Lecture Notes in Computer Science*, pages 64–78. Springer International Publishing.